Show intermediate results at all steps!

1. Consider the following homogeneous ODE with smooth coefficient $f(\cdot)$:

$$\frac{du(t)}{dt} = f(u). \tag{1}$$

Show that the Local Truncation Error of the following midpoint method is of order $O(k^2)$:

$$U^{n+1} = U^n + kf\left(U^n + \frac{1}{2}kf(U^n)\right).$$

2. The Asymptotic stability of a numerical method can studied through the Harmonic oscillator

$$\frac{dz}{dt} = Az$$
, where $A = \begin{bmatrix} 0 & 1\\ -\omega^2 & 0 \end{bmatrix}$, $z = (q, v)^T$.

Derive the stability condition for the Verlet algorithm:

$$q^{n+1} = q^n + kv^{n+1/2},$$

$$v^{n+1/2} = v^n - \frac{k}{2}\omega^2 q^n,$$

$$v^{n+1} = v^{n+1/2} - \frac{k}{2}\omega^2 q^{n+1}.$$

3. Prove the global convergence of the Euler scheme for equation (1):

$$U^{n+1} = U^n + kf(U^n).$$

4. Consider the Hamiltonian dynamics:

.

$$\frac{dq}{dt} = \nabla_p H(q, p), \quad \frac{dp}{dt} = -\nabla_q H(q, p).$$

Show that the implicit Euler-B scheme is symplectic

$$q^{n+1} = q^n + \Delta t \nabla_p H(q^n, p^{n+1}), \quad p^{n+1} = p^n - \Delta t \nabla_q H(q^n, p^{n+1}).$$

5. Consider linear equation

$$\frac{dz}{dt} = Az$$
, where $A = \begin{bmatrix} 0 & \omega \\ -\omega & 0 \end{bmatrix}$, $z = (q, p)^T$.

Derive the phase shift of the explicit Euler scheme.

6. For rigid body problem $q_i = q_{cm} + Qr_i^0$, i = 1, 2, ..., k, with $Q^T Q = I_3$. Give the Hamiltonian dynamics for (q_{cm}, Q) and its momentum under external potential $V_{ext}(q_{cm}, Q)$, and formulate the Rattle Scheme for simulation.